## ГЕОМЕТРИЯ И ТОПОЛОГИЯ

Председатель секции – профессор И.В. Белько Заместитель председателя секции – Ю.Я. Романовский

## ON AN ALMOST HYPERHERMITIAN STRUCTURE ON A LOCALLY K-SYMMETRIC RIEMANNIAN SPACE

S.A. Bogdanovich (BSPU, Minsk)

**Definition** [1]. A connected Riemannian manifold (M,g) with a family of local isometries  $\{s_x : x \in M\}$  is called a locally k-symmetric Riemannian space (k-s.l.R.s.) if the following axioms are fulfilled:

a)  $s_x(x) = x$  and x is the isolated fixed point of the local symmetry

 $s_x$ ;
b) the tensor field S:  $S_x = (s_{x*s})$  is smooth and invariant under any local isometry  $s_x$ ;

c)  $S^k = I$  and k is the least of such positive integers.

If M is a k-s.l.R.s. and  $X, Y \in \chi(M)$  then the unique canonical connection  $\widetilde{\nabla}$  can be defined by the following formula (see [2])

$$\widetilde{\nabla}_X Y = \nabla_X Y - \frac{1}{k} \sum_{j=1}^{k-1} \nabla_X (S^j) Y^{k-j} Y = \frac{1}{k} \sum_{j=0}^{k-1} S^j \nabla_X S^{k-j} Y.$$
 (1)

Further, we have  $\widetilde{\nabla}g=\widetilde{\nabla}\widetilde{R}=\widetilde{\nabla}h=\widetilde{\nabla}S=0,\ S(\widetilde{R})=\widetilde{R},\ S(h)=h,\ S(g)=g,$  where  $h=\nabla-\widetilde{\nabla}$  and  $\widetilde{R}$  is the curvature tensor field of  $\widetilde{\nabla}$ .

Let M be such a k-s.l.R.s. that  $S_x = (s_x)_{*x}$  has only complex eigenvalues  $a_1 \pm b_1 i$ , ...,  $a_r \pm b_r i$ . We define distributions  $D_i$ , i = 1, ..., r by  $D_i = ker(S^2 - 2a_i S + I)$ .

Every  $X \in \chi(M)$  has the unique decomposition  $X = X_1 + ... + X_r$ , where  $X_i \in D_i$ , i = 1, ..., r. An almost complex structure J on M is defined by

$$JX = \sum_{i=1}^{r} \frac{1}{b_i} (S - a_i I) X_i.$$
 (2)

It is proved in [2] that (M, g) is an almost Hermitian structure and the connection  $\widetilde{\nabla}$  defined by (1) coincides with the canonical connection  $\overline{\nabla}$  of the pair (J, g).

**Theorem.** Let  $(J_1, J_2, J_3, g)$  be such an almost hyperHermitian structure on a k-s.l.R.s. that  $J_1 = J$  where J is defined by (2). In this case  $J_2$  and  $J_3$  are not invariant with respect to the family  $\{s_x : x \in M\}$  and, therefore, with respect to the corresponding transitive pseudogroup of transformations of (M, g).

## References

- [1] Kowalski O. Generalized symmetric space // Lecture Notes in Math. 805. - Springer-Verlag, 1980.
- [2] Ermolitski A.A. Riemannian manifolds with geometric structures. -Minsk: BSPU, 1998.

## DEFORMATIONS OF STRUCTURES ON A TUBULAR NEIGHBORHOOD OF A SUBMANIFOLD

A.A. Ermolitski (Minsk)

Let M' be a k-dimensional manifold isometrically embedded in a ndimensional Riemannian manifold (M,g) and  $Tb(M';\varepsilon)=\bigcup_{p\in M'}D(p;\varepsilon)$ be the normal tubular neighborhood of the submanifold M' in M. There exist coordinates  $x_1,...,x_k$  in some neighborhood  $V_0\subset M$  of a point  $o \in M'$  and for any point  $x \in W_0 = \bigcup_{p \in V_0} D_p$  there exists such unique point  $p \in V_0$  that  $x = exp_p(t\xi)$ ,  $\|\xi\| = 1, \xi \in T_pM'^{\perp}$ . The point  $x \in W_0$  has the coordinates  $x_1, ..., x_k, x_{k+1}, ..., x_n$  where  $x_1, ..., x_k$  are coordinates of the point p in  $V_0$  and  $x_{i+1}, ..., x_n$  are normal coordinates of x in  $D_p$ . We denote  $X_i = \frac{\partial}{\partial x_i}$   $\sqrt{1, n}$ , on  $W_0$ .

Let K be a smooth tensor field of type (r,s) on the manifold Mand for  $x \in W_0$ 

and for 
$$x \in W_0$$

$$K_x = \sum_{i_1, \dots, i_r, j_1, \dots, j_s} K_{11 \dots, j_s}^{(11 \dots, i_r)}(x) X_{i_{1_x}} \otimes \dots \otimes X_{i_{r_x}} \otimes X_x^{j_1} \otimes \dots \otimes X_x^{j_s},$$

$$K_x = \sum_{i_1, \dots, i_r, j_1, \dots, j_s} K_{11 \dots, j_s}^{(11 \dots, i_r)}(x) X_{i_{1_x}} \otimes \dots \otimes X_{i_{r_x}} \otimes X_x^{j_1} \otimes \dots \otimes X_x^{j_s},$$

where  $\{X_x^1,...,X_x^n\}$  is the dual basis of  $T_x^*(M)$ ,  $x=exp_p(t\xi)$ ,  $\|\xi\|=1$ ,  $\xi \in T_p M'^{\perp}$ .

We consider a tensor field  $\overline{K}$  on M

We consider a tensor field 
$$X$$
 of  $X$   $X_{i_{r_x}} \otimes X_{i_{r_x}} \otimes X_{i$ 

by the following cases

a)  $x \in D(p; \frac{\varepsilon}{2}), z = p;$  b)  $x \in D(p; \varepsilon) \setminus D(p; \frac{\varepsilon}{2}), z = exp_p(2t - \varepsilon)\xi;$ 

c)  $x \in M \setminus Tb(M'; \varepsilon), z = x.$ 

It is easy to see the independence of the tensor field  $\overline{K}$  on a choice of coordinates in  $W_0$  for every point  $o \in M'$ .

The tensor field  $\overline{K}$  is called a deformation of the tensor field K on a tubular neighborhood of the submanifold M'.

The obtained tensor field  $\overline{K}$  is continuous but is not smooth on the boundaries of  $Tb(M'; \frac{\varepsilon}{2})$  and  $Tb(M'; \varepsilon)$ ,  $\overline{K}$  is smooth in other points of M.